1 Modeling Partial Functions with Total Structures

Traditionally, algebras or structures are total in the sense that they assign total functions to the function symbols of their signature.

Contrary to this, most working mathematicians would be very unhappy if they were not able to use partial functions. Similarly, some people working on algebraic specification are very fond of partial functions: The idea that a function symbol denotes a partial function results in so-called *partial* algebras, cf. the fascinating book of Reichel (1987), which, however, already makes clear that partial algebras are not as simple as total ones. Similarly, category theorists deal with *co* algebras, where partiality can easily be modeled because the co domain of a function symbol of a co signature is a sum into that $1 = \{\bot\}$ can nicely be included without the usual inconvenience of an extra sort for possibly erroneous values, cf. e.g. Jacobs & Rutten (1997), Padawitz (2000).

Again contrary to this, total algebras are preferred by computer scientists working on theorem proving and algebra in implementations that deal with a very big number of terms. This is because the soundness of these implementations requires that each occurring term object really is a term, and it is practically not possible to prove this again and again. Note that e.g. in a partial or co algebra containing the natural numbers nat and the predecessor function $\mathsf{p} : \mathsf{nat} \rightsquigarrow \mathsf{nat}$ or $\mathsf{p} : \mathsf{nat} \to \mathsf{nat} + 1$, resp., and a ground term t of sort nat, whether $\mathsf{p}(t)$ is defined or of sort nat and whether $\mathsf{p}(\mathsf{p}(t))$ is a term or not depends on the evaluation of t in the algebra and therefore is a semantical notion instead of a purely syntactical one. Thus, to our opinion, the terms of partial or co signatures do not satisfy the requirements for a practical implementation.

Our solution to this dilemma is to model partial functions with total algebras, cf. Wirth & Gramlich (1994b).

Consider a partial algebra $\mathcal{D}$ that assigns to each sort $s \in \mathbb{S}$ and each constant $f : s_0, \ldots, s_{n-1} \rightsquigarrow s_n$ of its signature Σ a non-empty set say $s^{\mathcal{D}}$ and a (strict) (possibly) partial function $f^{\mathcal{D}} : s_0^{\mathcal{D}} \times \cdots \times s_{n-1}^{\mathcal{D}} \rightsquigarrow s_n^{\mathcal{D}}$, resp.. We model this partial algebra with a class K of (total) Σ-*structures* $\mathcal{A}$ of the following form: $\mathcal{A}$ assigns to each sort $s \in \mathbb{S}$ and each constant $f : s_0, \ldots, s_{n-1} \rightsquigarrow s_n$ of Σ, resp., two non-empty sets say $(\mathrm{DAT}, s)^{\mathcal{A}}$ and $(\mathrm{GEN}, s)^{\mathcal{A}}$ with $(\mathrm{DAT}, s)^{\mathcal{A}} = s^{\mathcal{D}}$ and $(\mathrm{DAT}, s)^{\mathcal{A}} \subseteq (\mathrm{GEN}, s)^{\mathcal{A}}$, and a total function

$$f^{\mathcal{A}} : (\mathrm{GEN}, s_0)^{\mathcal{A}} \times \cdots \times (\mathrm{GEN}, s_{n-1})^{\mathcal{A}} \to (\mathrm{GEN}, s_n)^{\mathcal{A}}$$

with $f^{\mathcal{D}} \subseteq f^{\mathcal{A}}$. We call $(\mathrm{GEN}, s)^{\mathcal{A}}$ the *general universe of* $\mathcal{A}$ *for the sort* s, whereas $(\mathrm{DAT}, s)^{\mathcal{A}}$ is called the *data universe of* $\mathcal{A}$ *for the sort* s.

Let us define a *variable-system* for a set $\mathbb{S}$ of sorts and a set $\mathbb{K}$ of constants (= non-variable function symbols) to be a $\{\mathrm{GEN}, \mathrm{DAT}\} \times \mathbb{S}$-sorted family $\mathrm{V} = (\mathrm{V}_{\varsigma,s})_{(\varsigma,s) \in \{\mathrm{GEN},\mathrm{DAT}\} \times \mathbb{S}}$ of sets $\mathrm{V}_{\varsigma,s}$ that are mutually disjoint and disjoint from $\mathbb{K}$. The variables from $\mathrm{V}_{\mathrm{DAT},s}$ and $\mathrm{V}_{\mathrm{GEN},s}$ are called the *data* and *general variables of sort* s, resp.. By abuse of notation we sometimes write V to denote $\bigcup_{(\varsigma,s) \in \{\mathrm{GEN},\mathrm{DAT}\} \times \mathbb{S}} \mathrm{V}_{\varsigma,s}$, &c.. For k being any of these kinds of variables and for a term, formula Γ &c., '$\mathcal{V}_k(\Gamma)$' denotes the set of variables from V_k occurring in Γ.

The set $\mathcal{T}(\Sigma, \mathrm{V})_{\mathrm{GEN},s}$ of *terms of sort* s denotes the well-sorted first-order terms of fixed arity over $\mathbb{K}$ and V of sort $s \in \mathbb{S}$, where $\mathbb{S}$ and $\mathbb{K}$ are the set of sorts and the set of constants given by Σ, resp.. This means that, for $s \in \mathbb{S}$, the $\mathcal{T}(\Sigma, \mathrm{V})_{\mathrm{GEN},s}$ are the smallest sets such

that $\mathrm{V}_{\mathrm{GEN},s} \uplus \mathrm{V}_{\mathrm{DAT},s} \subseteq \mathcal{T}(\Sigma,\mathrm{V})_{\mathrm{GEN},s}$ and if $f : s_0,\ldots,s_{n-1} \rightsquigarrow s_n$ $(n \in \mathbf{N};\ s_0,\ldots,s_n \in \mathbb{S})$ and, for each $i \prec n$, $t_i \in \mathcal{T}(\Sigma,\mathrm{V})_{\mathrm{GEN},s_i}$ then $f(t_0,\ldots,t_{n-1}) \in \mathcal{T}(\Sigma,\mathrm{V})_{\mathrm{GEN},s_n}$. The set $\mathcal{T}(\Sigma,\mathrm{V})_{\mathrm{DAT},s}$ of *data terms of sort s* denotes the subclass of terms from $\mathcal{T}(\Sigma,\mathrm{X})_{\mathrm{GEN},s}$ that only contain variables from $\mathrm{V}_{\mathrm{DAT}}$ and constants from a special set $\mathbb{C} \subseteq \mathbb{K}$ of *constructors* that is given by the signature Σ. For such a constructor $c \in \mathbb{C}$ with $c : s_0,\ldots,s_{n-1} \to s_n$ we require that any Σ-structure $\mathcal{A}$ must satisfy

$$\forall i \prec n.\ d_i \in (\mathrm{DAT},s_i)^{\mathcal{A}} \quad\Rightarrow\quad c^{\mathcal{A}}(d_0,\ldots,d_{n-1}) \in (\mathrm{DAT},s_n)^{\mathcal{A}}.$$

Let $T = (T_{\varsigma,s})_{(\varsigma,s)\in\{\mathrm{GEN},\mathrm{DAT}\}\times\mathbb{S}}$ be any $\{\mathrm{GEN},\mathrm{DAT}\}\times\mathbb{S}$-sorted family of sets. With $\mathrm{V} \to T$ we denote the ($\{\mathrm{GEN},\mathrm{DAT}\}\times\mathbb{S}$-sorted) (total) functions from V to T. On the one hand, if T is a family of sets of terms, then the elements of $\mathrm{V} \to T$ are *substitutions*. E.g., if $\sigma : \mathrm{V} \to \mathcal{T}(\Sigma,\mathrm{V})$, then, for any $X \in \mathrm{V}_{\mathrm{GEN},s}$, $\sigma(X)$ is a term of sort s, and for any $x \in \mathrm{V}_{\mathrm{DAT},s}$, $\sigma(x)$ is a data term of sort s. For a substitution σ we denote with '$\Gamma\sigma$' the result of replacing in Γ each occurrence of any variable $x \in \mathrm{dom}(\sigma)$ with $\sigma(x)$. On the other hand, if T is a Σ-structure $\mathcal{A}$, then we use $\mathcal{A}$ to denote $((\varsigma,s)^{\mathcal{A}})_{(\varsigma,s)\in\{\mathrm{GEN},\mathrm{DAT}\}\times\mathbb{S}}$ and the elements of $\mathrm{V} \to \mathcal{A}$ are the (total) valuations from V to $\mathcal{A}$.

For $\tau : \mathrm{V} \to \mathcal{A}$ we denote with '$\mathcal{A}\uplus\tau$' the extension of $\mathcal{A}$ to the variables of V which are then treated as nullary constants. More precisely, we assume the existence of some evaluation function 'eval' such that $\mathrm{eval}(\mathcal{A}\uplus\tau)$ maps any term over $\Sigma\uplus\mathrm{V}$ into the universe of $\mathcal{A}$ (respecting kinds) such that for all $x \in \mathrm{V}$: $\mathrm{eval}(\mathcal{A}\uplus\tau)(x) = \tau(x)$. Moreover, $\mathrm{eval}(\mathcal{A}\uplus\tau)$ maps any formula B over $\Sigma\uplus\mathrm{V}$ to TRUE or FALSE, such that B is valid in $\mathcal{A}\uplus\tau$ iff $\mathrm{eval}(\mathcal{A}\uplus\tau)(B) = \mathsf{TRUE}$. We assume that the *Substitution-Lemma* (cf. e.g. Enderton (1973), p. 127, or Fitting (1996), p. 120) holds in the sense that, for any substitution σ, Σ-structure $\mathcal{A}$, valuation $\tau : \mathrm{V} \to \mathcal{A}$, and term or formula B over $\Sigma\uplus\mathrm{V}$:

$$\mathrm{eval}(\mathcal{A}\uplus\tau)(B\sigma) = \mathrm{eval}\big(\ \mathcal{A}\ \uplus\ (\ \sigma\ \uplus\ {}_{\mathrm{V}\setminus\mathrm{dom}(\sigma)}|\mathrm{id}\ )\ \circ\ \mathrm{eval}(\mathcal{A}\uplus\tau)\ \big)\big(\ B\ \big).$$

Note that we assume the operator '$\circ$' to have higher priority than the operators '$\cup$' and '$\uplus$'.

Now, when the partial algebra $\mathcal{D}$ satisfies a first-order specification where all terms are defined and when we consider all variables occurring in this specification to be from $\mathrm{V}_{\mathrm{DAT}}$, then the specification is satisfied by each Σ-structure $\mathcal{A}$ in our above class K. Note that the variables from $\mathrm{V}_{\mathrm{GEN}}$ are useful for specifying non-strict partial functions:

Example 1.1
Let $\mathsf{true},\mathsf{false} : \mathsf{bool}$ be the constructors for the sort bool of Boolean values. Let $\mathsf{or} : \mathsf{bool},\mathsf{bool} \to \mathsf{bool}$ be from $\mathbb{K}\setminus\mathbb{C}$. Let $X : \mathrm{V}_{\mathrm{GEN},\mathsf{bool}}$ and $x : \mathrm{V}_{\mathrm{DAT},\mathsf{bool}}$. Let t be a ground term of sort bool that does not evaluate to the data universe of sort bool given by the values of true and false under the evaluation function. Now specifying or via $\mathsf{or}(x,\mathsf{false})=x$ and $\mathsf{or}(x,\mathsf{true})=\mathsf{true}$ has the same syntactical and semantical effect as specifying it via $\mathsf{or}(\mathsf{true},\mathsf{true})=\mathsf{true}$, $\mathsf{or}(\mathsf{false},\mathsf{true})=\mathsf{true}$, $\mathsf{or}(\mathsf{true},\mathsf{false})=\mathsf{true}$, $\mathsf{or}(\mathsf{false},\mathsf{false})=\mathsf{false}$. Moreover, adding $\mathsf{or}(\mathsf{true},x)=\mathsf{true}$ has no effect anymore. Contrariwise, $\mathsf{or}(X,\mathsf{false})=X$, $\mathsf{or}(X,\mathsf{true})=\mathsf{true}$ also specifies that $\mathsf{or}(t,\mathsf{true})=t$ and adding $\mathsf{or}(\mathsf{true},X)=\mathsf{true}$ has the additional effect of implying $\mathsf{or}(\mathsf{true},t)=\mathsf{true}$. By the way, the readers familiar with rewriting systems may note that all these equations do not produce a single proper critical pair.

Continuing our modeling of partiality, we add a predicate Def_s on s (index omitted when clear from context) for each sort s of Σ that is interpreted by any Σ-structure $\mathcal{A}$ as $(\mathrm{DAT}, s)^{\mathcal{A}}$. Now, if a ground term t over Σ is defined w.r.t. $\mathcal{D}$, then $\mathrm{Def}\, t$ holds in each Σ-structure $\mathcal{A}$ of our above class K. The converse is also true, provided that K contains all possible Σ-structures of the above kind. To wit, include the Σ-structure given by $(\mathrm{GEN}, s)^{\mathcal{A}} = (\mathrm{DAT}, s)^{\mathcal{A}} \uplus \{\bot\}$ and the functions evaluating to $\bot$ when undefined in $\mathcal{D}$ or when applied to $\bot$. Considering this Σ-structure, the question arises what the possibility to choose $(\mathrm{GEN}, s)^{\mathcal{A}}$ different from $(\mathrm{DAT}, s)^{\mathcal{A}} \uplus \{\bot\}$ is good for. The simple answer is that, on one hand, we want to be able to model non-strict functions like or in Example 1.1 above and, on the other hand, we do not want silly theorems to hold or to be undefined on the meta-level, like $\frac{0}{0}{=}\mathsf{p}(0)$ (due to $\bot{=}\bot$) that becomes invalid when we add $\mathsf{p}(0) = 0$ to the specification of natural numbers.

Well-known equality notions like (in order of increasing logical strength) *weak*, *strong*, and *existential* equality of two terms t, t' can now be expressed via $t{=}t' \Leftarrow (\mathrm{Def}\, t \wedge \mathrm{Def}\, t')$, $(t{=}t' \wedge \mathrm{Def}\, t \wedge \mathrm{Def}\, t') \vee (\neg\mathrm{Def}\, t \wedge \neg\mathrm{Def}\, t')$, and $t{=}t' \wedge \mathrm{Def}\, t \wedge \mathrm{Def}\, t'$, resp., but this is not our subject here.

Since, in our modeling, the notion of a term is a purely syntactical one and for reasons we will see later, this modeling of partial functions with total Σ-structures makes the computer scientists perfectly happy. People working on partial or co algebras in practice should also be interested in it. Finally, the working mathematicians are confident with our modeling because they are not really interested in the logical formalization of partial functions, at least as long as there is one and someone who could principally formalize the proofs containing partial functions.

2 Data Universes

In this section we discuss two ways of establishing partial algebras $\mathcal{D}$ that we are going to use as the common data reduct of our class K of Σ-algebras of the Σ-structures of our class of models as explained in § 1.

In order to do this, we first add some more slots to our signature objects. We assume that each signature Σ contains a wellfounded quasi-ordering $\lesssim$ on $\mathbb{S}$, and two disjoint sets $\mathbb{V}$ and $\mathbb{H}$ of *visible* and *hidden sorts*, resp., that partition the set of sorts $\mathbb{S}$, i.e. $\mathbb{S} = \mathbb{V} \uplus \mathbb{H}$.

Moreover, we require that the equivalence classes of the quasi-ordering $\lesssim$ (i.e. those of the equivalence $\sim := \lesssim \cap \gtrsim$) are subclasses of $\mathbb{V}$ or $\mathbb{H}$. Now, the data universes of such an equivalence class of sorts are built up in parallel, assuming that the data universes for all sorts strictly smaller in the ordering $<$ have already been established. The manner in that this is done depends on whether the equivalence class is a subclass of $\mathbb{V}$ or of $\mathbb{H}$, as discussed in the following two subsections. While visible sorts are standard, hidden sorts are still not generally understood.

2.1 Visible Sorts and Constructors

For any constructor $c \in \mathbb{C}$ with say $c : s_0, \ldots, s_{n-1} \to s_n$ $(n \in \mathbf{N})$ we require that $s_n \in \mathbb{V}$ and $\forall i \prec n.\ s_i \lesssim s_n$, and call c a *constructor for* s_n. Let V be the equivalence class of s_n w.r.t. $\sim$. For any $d_i \in s_i^{\mathcal{D}}$ $(i \prec n)$, the term $c(d_0, \ldots, d_{n-1})$ becomes an element in $s_n^{\mathcal{D}}$. While the $s_i^{\mathcal{D}}$ with $s_i < s_n$ are assumed to be already given, all $v^{\mathcal{D}}$ with $v \in V$ are being defined as the smallest sets closed under the above term construction with all constructors for v. Moreover, in order to avoid empty data universes, we require that, for each $v \in V$, there is a term of sort v that only consists of constructors for the sorts in V and variables of sorts say s' with $s' < s_n$. Finally, in the above context, we define $c^{\mathcal{D}}(d_0, \ldots, d_{n-1}) := c(d_0, \ldots, d_{n-1})$, which immediately gives us the required $c^{\mathcal{D}}(d_0, \ldots, d_{n-1}) \in s_n^{\mathcal{D}}$, i.e. the totality of $c^{\mathcal{D}} : {s_0}^{\mathcal{D}} \times \cdots \times {s_{n-1}}^{\mathcal{D}} \to {s_n}^{\mathcal{D}}$.

Example 2.1
The and/or and or/and trees over bool can be realized with the visible sorts and and or, resp., when we set $\mathsf{bool} < \mathsf{or} \sim \mathsf{and}$ and take as constructors

$$[_]^{\mathsf{or}}_{\mathsf{bool}} : \mathsf{bool} \to \mathsf{or}, \quad [_]^{\mathsf{or}}_{\mathsf{and}} : \mathsf{and} \to \mathsf{or}, \quad \mathsf{cons}_{\mathsf{or}} : \mathsf{and}, \mathsf{or} \to \mathsf{or},$$
$$[_]^{\mathsf{and}}_{\mathsf{bool}} : \mathsf{bool} \to \mathsf{and}, \quad [_]^{\mathsf{and}}_{\mathsf{or}} : \mathsf{or} \to \mathsf{and}, \quad \mathsf{cons}_{\mathsf{and}} : \mathsf{or}, \mathsf{and} \to \mathsf{and}.$$

An and/or tree like $\wedge(a, \vee(b, c, \wedge(d, \vee(e)), f))$ is then represented as the term

$$\mathsf{cons}_{\mathsf{and}}([a]^{\mathsf{or}}_{\mathsf{bool}}, [\mathsf{cons}_{\mathsf{or}}([b]^{\mathsf{and}}_{\mathsf{bool}}, \mathsf{cons}_{\mathsf{or}}([c]^{\mathsf{and}}_{\mathsf{bool}}, \mathsf{cons}_{\mathsf{or}}(\mathsf{cons}_{\mathsf{and}}([d]^{\mathsf{or}}_{\mathsf{bool}}, [[e]^{\mathsf{or}}_{\mathsf{bool}}]^{\mathsf{and}}_{\mathsf{or}}), [f]^{\mathsf{or}}_{\mathsf{bool}})))]^{\mathsf{and}}_{\mathsf{or}}).$$

While the presentation of this term to human beings cries for some syntactic sugaring, the term can well serve as an implementation and has the advantage that all children of the root of an and/or-tree are guaranteed to be or/and-trees, provided that the term is well-sorted.

Note that, theoretically, any data universe can be established with a visible sort simply by introducing a nullary constructor symbol for exactly each element of the intended data universe.

Summing up, the data universes for visible sorts are built up the following way:

No Junk

One starts with the empty set and keeps adding terms that apply a constructor. This process will come to an end at level ω. Another way to say this is that the data universes are the least fixpoints of the finitary and monotonic functor that returns the set of terms that apply a constructor to its argument set. The buzzword "no junk" emphasizes that the data universes contain nothing but what is generated by the constructors as useful data.

No Confusion

All elements that have a different construction process are considered to be different. The buzzword "no confusion" actually only means that there is as little equality between the elements as possible or, stated differently, that the universe can be homomorphically mapped to any other universe that satisfies some required axioms. E.g., when we used lists to represent finite sets, we would need the axioms of associativity, commutativity, and idempotence. In former papers we used to allow such axioms in the form of positive conditional constructor equations. Since these constructor equations produced a lot of trouble regarding consistency and theorem proving we did not include them in the implementation of the tactic-based inductive theorem prover QuodLibet, cf. Kühler (2000), and by now we also do not want to have them in our theoretical considerations anymore because we can have sets as a hidden sort and the finite sets are simply those where the function $\mathsf{card} : \mathsf{set} \rightsquigarrow \mathsf{nat}$ is defined.

In Wirth & Gramlich (1994b) we even had types of validity where junk or confusion could occur in the data universes for visible sorts. Today we do not consider this to be appropriate anymore.

2.2 Hidden Sorts and Destructors

Definition 2.2 (Condition Literal)
Let Σ be a signature, X be a variable-system for $\mathbb{S}, \mathbb{K}$, and $s \in \mathbb{S}$.
A *condition literal over* Σ, X *of sort* s has one of the following forms

$\mathrm{Def}_s u$ where $u \in \mathcal{T}(\Sigma, \mathrm{X})_{\mathrm{GEN},s}$.
This literal is not *conjugatible* and its *terms* are the single term u.

$u_0 =_s u_1$ where $u_0, u_1 \in \mathcal{T}(\Sigma, \mathrm{X})_{\mathrm{GEN},s}$.
This literal is *conjugatible* to its *conjugate* $u_0 \neq_s u_1$. Its *terms* are u_0, u_1.

$u_0 \neq_s u_1$ where $u_0, u_1 \in \mathcal{T}(\Sigma, \mathrm{X})_{\mathrm{GEN},s}$.
This literal is *conjugatible* to its *conjugate* $u_0 =_s u_1$. Its *terms* are u_0, u_1.

The sort indices are omitted when clear from the context. The conjugate of a conjugatible condition literal is denoted by $\overline{L}$.

Let $H \subseteq \mathbb{H}$ be the equivalence class of hidden sorts whose data universes we want to establish and O the set of sorts from $\mathbb{S}$ whose data universes we assume to be already established because they are smaller than the sorts in H w.r.t. $<$.

We first add some more slots to our signature objects. We assume that each signature Σ contains a set $\mathbb{D} \subseteq \mathbb{K}\backslash\mathbb{C}$ of *destructors*, a function $\bullet$ with $\mathrm{dom}(\bullet) = \mathbb{H}$ and $\bullet_h \in \mathrm{V}_{\mathrm{GEN},h}$ for all $h \in \mathbb{H}$, and a set $\mathbb{P}$ of *destructor patterns*.

Definition 2.3 (Destructor Pattern)
Each *destructor pattern* from $\mathbb{P}$ has the form $d(x_0,\ldots,x_n) \longleftarrow L_0,\ldots,L_{m-1}$ where $n,m \in \mathbf{N}$ (for $m=0$ we omit the '$\longleftarrow$'); $d \in \mathbb{D}$ is a destructor with $d : s_0,\ldots,s_n \rightsquigarrow s_{n+1}$; $x_0,\ldots,x_n \in \mathrm{V}_{\mathrm{DAT}}$ are mutually different data variables; and there is an $i \preceq n$ with $\mathrm{ran}(\bullet) \cap \{x_0,\ldots,x_n\} = \{\bullet_{s_i}\}$, $\forall k \preceq n{+}1.\ s_k \lesssim s_i$, and for each $j \prec m$, L_j is a conjugatible condition literal over the constructors and destructors for sorts from $O \uplus H$ and over $x_0,\ldots,x_n$ and of a sort from O. In this case, we speak of a destructor pattern *for* s_i *and of sort* s_{n+1}, denote the set of these patterns with $\mathbb{P}^{s_{n+1}}_{s_i}$, and call d a destructor *for* s_i *and of sort* s_{n+1}.

While a destructor pattern can be for only one sort, a destructor can be for different sorts (in different patterns), but we require that these sorts are congruent w.r.t. $\sim$.

Note that the wellfounded quasi-ordering $\lesssim$ guarantees that visible sorts are not constructed from hidden sorts whose behavior they define, which would be a vicious circle. Thus, the result sort of a constructor must be visible and its argument sorts must be smaller, whereas the hidden argument sorts of a destructor must be somehow bigger than its result sort, the sorts of its arguments, and the sorts of the condition literals of its destructor patterns. Note that in the absence of hidden sorts we can choose $\lesssim$ to be $\mathbb{V}\times\mathbb{V}$. This renders the conditions imposed on a signature to be satisfied, so that our signatures really are a generalization of the standard constructor-based notion of a sensible (or inhabited) many-sorted signature to one with hidden sorts and destructors.

Assume that $\mathcal{D}$ assigns to each sort in O and its constructors the already established universes and total functions. Moreover, assume that $\mathcal{D}$ assigns to any destructor for hidden sorts in O already established partial functions. The step we have to perform is to let $\mathcal{D}$ assign a data universe to each sort in H and a partial function to each destructor for a sort in H. Suppose we have a candidate $\mathcal{D}$ for such an assignment.

Firstly, we need three requirements for $\mathcal{D}$. The first is needed soon, the other two must be formulated later.

Requirement 2.4 (Definedness)
For each destructor pattern $\big(\ d(x_0,\ldots,x_n) \longleftarrow L_0,\ldots,L_{m-1}\ \big) \in \mathbb{P}^s_h$ *($h \in H$) we require that for each valuation* $\tau : \{x_0,\ldots,x_n\} \to \mathcal{D}$,

- *for each* $j \prec m$ *the terms of* L_j *are defined w.r.t.* $\mathcal{D}\uplus\tau$ *if the literals* $L_0,\ldots,L_{j-1}$ *are true w.r.t.* $\mathcal{D}\uplus\tau$ *and*
- $d(x_0,\ldots,x_n)$ *is defined w.r.t.* $\mathcal{D}\uplus\tau$ *if the literals* $L_0,\ldots,L_{m-1}$ *are true w.r.t.* $\mathcal{D}\uplus\tau$.

Moreover, we require that the domain of the destructors for H *is the smallest one satisfying the above monotonic closure condition.*

Secondly, we define the following:

Definition 2.5 (Bisimulation)
A $\mathbb{P}$*-bisimulation for* $\mathcal{D}$ is an $O \uplus H$-sorted family $\approx = (\approx_s)_{s \in O \uplus H}$ of binary relations $\approx_s$ on $s^{\mathcal{D}}$ that has the following properties:

1. For $o \in O$ we have $a \approx_o a'$ iff $a = a' \in o^{\mathcal{D}}$.
2. For $h \in H$, if $a \approx_h a'$ and $\left(t \longleftarrow L_0, \ldots, L_{m-1} \right) \in \mathbb{P}^s_h$, for $Y := \mathcal{V}(t) \backslash \{\bullet_h\}$ and $\forall y \in Y.\ y \in \mathrm{V}_{\mathrm{DAT}, s'_y}$, for any $\pi : Y \to \mathcal{D}$

   either there are some $i, i' \prec m$ such that
   all terms of $L_0, \ldots, L_i$ are defined and L_i is false w.r.t. $\mathcal{D} \uplus \{\bullet_h \mapsto a\} \uplus \pi$, and
   all terms of $L_0, \ldots, L_{i'}$ are defined and $L_{i'}$ is false w.r.t. $\mathcal{D} \uplus \{\bullet_h \mapsto a'\} \uplus \pi$,

   or otherwise t and all terms of $L_0, \ldots, L_{m-1}$ are defined and all literals of $L_0, \ldots, L_{m-1}$ are true w.r.t. $\mathcal{D} \uplus \{\bullet_h \mapsto a\} \uplus \pi$ and w.r.t. $\mathcal{D} \uplus \{\bullet_h \mapsto a'\} \uplus \pi$ and $\mathrm{eval}(\mathcal{D} \uplus \{\bullet_h \mapsto a\} \uplus \pi)(t) \approx_s \mathrm{eval}(\mathcal{D} \uplus \{\bullet_h \mapsto a'\} \uplus \pi)(t)$.

Definition 2.6 (Experiment)
Let Σ be a signature. For $h \in \mathbb{H}$ and $s \in \mathbb{V}$ the sets $\mathbb{E}^s_h$ of *experiments over* Σ *for* h *of sort* s are inductively defined as follows:

1. $\mathbb{P}^s_h \subseteq \mathbb{E}^s_h$.
2. If, for $h' \in \mathbb{H}$,
   $\left(e \longleftarrow L_0, \ldots, L_{m-1} \right) \in \mathbb{E}^s_{h'}$,
   $\left(e' \longleftarrow L'_0, \ldots, L'_{m'-1} \right) \in \mathbb{P}^{h'}_h$,
   $\sigma : \mathcal{V}(e) \to \mathcal{T}(\Sigma, \mathrm{V})$ satisfies $\sigma(\bullet_{h'}) = e'$ and renames $\mathcal{V}(e) \setminus \{\bullet_{h'}\}$ away from $\mathcal{V}(e')$ and $\mathrm{ran}(\bullet)$ (i.e. $_{\mathcal{V}(e) \backslash \{\bullet_{h'}\}} \restriction \sigma : (\mathcal{V}(e) \backslash \{\bullet_{h'}\}) \to (\mathrm{V} \backslash \mathcal{V}(e') \backslash \mathrm{ran}(\bullet))$ is injective), then
   $\left(e\sigma \longleftarrow L'_0, \ldots, L'_{m'-1}, L_0\sigma, \ldots, L_{m-1}\sigma \right) \in \mathbb{E}^s_h$.

Note that for any experiment $e \longleftarrow L_0, \ldots, L_{m-1}$ for h of sort s the following holds: the term e is linear, $\mathcal{V}(L_0, \ldots, L_{m-1}) \subseteq \mathcal{V}(e)$, and there is a unique path from the root of e to the variable $\bullet_h$. On this path, all proper subterms are hidden and all symbols are destructors, whereas all symbols not on this path are variables. Furthermore, $s < h$ and $l_j < h$ for the sorts l_j of L_j.

Now, an $\mathbb{E}$-*bisimulation* can be defined just like a $\mathbb{P}$-bisimulation in Definition 2.5 and the following corollary holds for $\mathbb{P}$- as well as for $\mathbb{E}$-bisimulations.

Corollary 2.7

1. *If $\mathcal{D}$ satisfies Requirement 2.4, then $({}_{s^{\mathcal{D}}}\!\upharpoonright\!\mathrm{id})_{s\in O\uplus H}$ is a bisimulation for $\mathcal{D}$.*
2. *If $(A_s)_{s\in O\uplus H}$ and $(B_s)_{s\in O\uplus H}$ are bisimulations for $\mathcal{D}$, then $(A_s^{-1})_{s\in O\uplus H}$ and $(A_s\circ B_s)_{s\in O\uplus H}$ are bisimulations for $\mathcal{D}$, too.*
3. *A non-empty union over bisimulations for $\mathcal{D}$ is a bisimulation for $\mathcal{D}$.*
4. *If $\mathcal{D}$ satisfies Requirement 2.4, then there is a maximum bisimulation for $\mathcal{D}$ which is given as the union over all bisimulations for $\mathcal{D}$ and is a $\mathcal{D}$-equivalence.*

Corollary 2.8 *Every $\mathbb{P}$-bisimulation is an $\mathbb{E}$-bisimulation.*

As the maximum $\mathbb{E}$-bisimulation can easily be shown to satisfy the contrapositive of condition (2) of the definition of a $\mathbb{P}$-bisimulation, we get:

Corollary 2.9 *If $\mathcal{D}$ satisfies Requirement 2.4, then the maximum $\mathbb{E}$-bisimulation for $\mathcal{D}$ is the maximum $\mathbb{P}$-bisimulation for $\mathcal{D}$ and will be denoted with $\approx_{\mathcal{D}}$.*

The second requirement on $\mathcal{D}$ is the opposite of "no confusion":

Requirement 2.10 (Extensionality)
For any two elements $a, a' \in h^{\mathcal{D}}$ of a data universe for a sort $h \in H$, if $a \approx_{\mathcal{D},h} a'$ then $a = a'$.

The third requirement on $\mathcal{D}$ is quite the opposite of "no junk":

Requirement 2.11 (Maximality)
If we extend the data universes for H and the partial functions for the destructors for H, yielding a new structure $\mathcal{D}'$ for that Requirement 2.4 is satisfied, then for each new element $a \in h^{\mathcal{D}'} \setminus h^{\mathcal{D}}$ of a data universe for $h \in H$, we have $a \approx_{\mathcal{D}',h} a'$ for some old element $a' \in h^{\mathcal{D}}$.

Now it is time to see some examples.

Example 2.12 (Infinite Streams)
The infinite streams over some sort s can be established as follows. Let $\mathsf{infstream} \in \mathbb{H}$ with $s < \mathsf{infstream}$ and $\mathsf{hd},\ \mathsf{tl} \in \mathbb{D}$ with $\mathsf{hd} : \mathsf{infstream} \rightsquigarrow s$ and $\mathsf{tl} : \mathsf{infstream} \rightsquigarrow \mathsf{infstream}$. Set $\mathbb{P} := \{\mathsf{hd}(\bullet_{\mathsf{infstream}}),\ \mathsf{tl}(\bullet_{\mathsf{infstream}})\}$. We get $\mathbb{E} = \{\ \mathsf{hd}(\mathsf{tl}^k(\bullet_{\mathsf{infstream}}))\ \mid\ k \in \mathbf{N}\ \}$.
The above definedness requirement says that $\mathsf{hd}^{\mathcal{D}}$ and $\mathsf{tl}^{\mathcal{D}}$ must be total on $\mathsf{infstream}^{\mathcal{D}}$.
The condition (2) of Definition 2.5 says (due to $Y = \emptyset$) that $a \approx_{\mathcal{D},\mathsf{infstream}} a'$ implies $\mathsf{hd}^{\mathcal{D}}(a) = \mathsf{hd}^{\mathcal{D}}(a')$ and $\mathsf{tl}^{\mathcal{D}}(a) \approx_{\mathcal{D},\mathsf{infstream}} \mathsf{tl}^{\mathcal{D}}(a')$.
Thus, the above extensionality requirement says that the data universe for $\mathsf{infstream}$ can be viewed as a subset of $\mathbb{E} \to s^{\mathcal{D}}$ (with simple changes for more general experiments (cf. Example 2.15), this is always the case if the experiments are unconditional and do not include variables of sorts from H besides $\mathrm{ran}(\bullet)$) or as a subset of $\mathbf{N} \to s^{\mathcal{D}}$. Indeed, the infinite

streams are isomorphic to this set of functions.
Finally, the maximality requirement says that we need all functions from $\mathbf{N} \to s^{\mathcal{D}}$ in the data universe for $\mathsf{infstream}$, or at least those we can talk about. By this we mean that we only need those streams that can be comprehended with our language, logic, and (co) recursive definition mechanism. Such a "Henkin" or "general" model can usually be guaranteed to exist, to be countable, and to have the same theory as the standard model (here: of all streams) by a proof similar to the completeness proof for Q_0 in Andrews (1986). While countable data universes may be preferred for philosophical reasons, for infinite streams there seems to be no real need to deviate from the standard model. This will be different in Example 2.16 below.
The co algebraic view on infinite streams is the destructor

$$(\mathsf{hd}, \mathsf{tl}) : \mathsf{infstream} \to s \times \mathsf{infstream}$$

and the set of infinite streams is the greatest fixpoint of the monotonic functor $F(X) = s^{\mathcal{D}} \times X$ in the non-wellfounded set theory of Aczel (1988).

Example 2.13 (Streams)
The (finite and infinite) streams over some sort s can be established as follows. Let $\mathsf{stream} \in \mathbb{H}$ with $s < \mathsf{stream}$ and $\mathsf{null}, \mathsf{hd}, \mathsf{tl} \in \mathbb{D}$ with $\mathsf{null} : \mathsf{stream} \rightsquigarrow \mathsf{bool}$, $\mathsf{hd} : \mathsf{stream} \rightsquigarrow s$, and $\mathsf{tl} : \mathsf{stream} \rightsquigarrow \mathsf{stream}$. Set

$$\mathbb{P} := \left\{ \begin{array}{lcl} \mathsf{null}(\bullet_{\mathsf{stream}}); & & \\ \mathsf{hd}(\bullet_{\mathsf{stream}}) & \longleftarrow & \mathsf{null}(\bullet_{\mathsf{stream}}){=}\mathsf{false}; \\ \mathsf{tl}(\bullet_{\mathsf{stream}}) & \longleftarrow & \mathsf{null}(\bullet_{\mathsf{stream}}){=}\mathsf{false} \end{array} \right\}.$$

We get $\mathbb{E} :=$

$$\left\{ \begin{array}{lcl} \mathsf{null}(\mathsf{tl}^k(\bullet_{\mathsf{stream}})) & \longleftarrow & \mathsf{null}(\mathsf{tl}^0(\bullet_{\mathsf{stream}})){=}\mathsf{false}, \ \ldots, \ \mathsf{null}(\mathsf{tl}^{k-1}(\bullet_{\mathsf{stream}})){=}\mathsf{false}; \\ \mathsf{hd}(\mathsf{tl}^k(\bullet_{\mathsf{stream}})) & \longleftarrow & \mathsf{null}(\mathsf{tl}^0(\bullet_{\mathsf{stream}})){=}\mathsf{false}, \ \ldots, \ \mathsf{null}(\mathsf{tl}^k(\bullet_{\mathsf{stream}})){=}\mathsf{false} \end{array} \middle| \ k \in \mathbf{N} \right\}.$$

The above definedness requirement says that $\mathsf{null}^{\mathcal{D}}$ must be total on $\mathsf{stream}^{\mathcal{D}}$ and that the domain of $\mathsf{hd}^{\mathcal{D}}$ and $\mathsf{tl}^{\mathcal{D}}$ must be the non-null streams.
The condition (2) of Definition 2.5 says that $a \approx_{\mathcal{D},\mathsf{stream}} a'$ implies $\mathsf{null}^{\mathcal{D}}(a) = \mathsf{null}^{\mathcal{D}}(a')$ and if $\mathsf{null}^{\mathcal{D}}(a) = \mathsf{false}^{\mathcal{D}}$ then $\mathsf{hd}^{\mathcal{D}}(a) = \mathsf{hd}^{\mathcal{D}}(a')$ and $\mathsf{tl}^{\mathcal{D}}(a) \approx_{\mathcal{D},\mathsf{stream}} \mathsf{tl}^{\mathcal{D}}(a')$.
Thus, the above extensionality requirement says that the data universe for stream can be viewed as a subset of $\bigcup_{\alpha \preceq \omega} (\alpha \to s^{\mathcal{D}})$. Indeed, the streams are isomorphic to this set of functions.
Finally, the maximality requirement says that we need all functions from this set in the data universe for stream, or at least those we can talk about.
The co algebraic view on infinite streams is the destructor

$$(\mathsf{hd}, \mathsf{tl}) : \mathsf{stream} \to s \times (\mathsf{stream} + 1)$$

and the set of streams minus the empty stream is the greatest fixpoint of the monotonic functor $F(X) = s^{\mathcal{D}} \times (X \uplus 1)$ in the non-wellfounded set theory of Aczel (1988).

Example 2.14 (Characteristic Functions)
The characteristic functions over some sort s can be established as follows. Let $\mathsf{chara} \in \mathbb{H}$ with $s < \mathsf{chara}$ and $\mathsf{in} \in \mathbb{D}$ with $\mathsf{in} : s, \mathsf{chara} \rightsquigarrow \mathsf{bool}$.
Set $\mathbb{P} := \{\mathsf{in}(e, \bullet_{\mathsf{chara}})\}$. We get $\mathbb{E} = \mathbb{P}$.
The above definedness requirement says that $\mathsf{in}^{\mathcal{D}}$ must be total on $s^{\mathcal{D}} \times \mathsf{chara}^{\mathcal{D}}$.
The condition (2) of Definition 2.5 says that $a \approx_{\mathcal{D},\mathsf{chara}} a'$ implies $\mathsf{in}^{\mathcal{D}}(e, a) = \mathsf{in}^{\mathcal{D}}(e, a')$ for any $e \in s^{\mathcal{D}}$.
Thus, the above extensionality requirement says that the data universe for chara can be

viewed as a subset of $s^{\mathcal{D}} \to \mathsf{bool}^{\mathcal{D}}$. Indeed, the characteristic functions are isomorphic to this set of functions.
Finally, the maximality requirement says that we need all functions from this set in the data universe for chara, or at least those we can talk about.
The co algebraic view on characteristic functions is the destructor $\mathsf{in} : \mathsf{chara} \to s \to 2$ and the set of characteristic functions is the greatest fixpoint of the monotonic functor $F(X) = s^{\mathcal{D}} \to \mathsf{bool}^{\mathcal{D}}$.

Example 2.15 (Total Functions)
The simple function spaces of simply typed higher-order logic can be established stepwise in the following fashion. For $\alpha, \beta \in \mathbb{S}$, in order to get the total functions from α to β, let $(\alpha \to \beta) \in \mathbb{H}$ with $\alpha, \beta < (\alpha \to \beta)$ and $\mathsf{app} \in \mathbb{D}$ with $\mathsf{app} : (\alpha \to \beta), \alpha \rightsquigarrow \beta$. Set $\mathbb{P} := \{\mathsf{app}(\bullet_{(\alpha\to\beta)}, a)\}$. We get $\mathbb{E} = \mathbb{P}$.
The above definedness requirement says that $\mathsf{app}^{\mathcal{D}}$ and must be total on $(\alpha \to \beta)^{\mathcal{D}} \times \alpha^{\mathcal{D}}$. The condition (2) of Definition 2.5 says (due to $Y = \emptyset$) that $f \approx_{\mathcal{D},(\alpha\to\beta)} f'$ implies $\mathsf{app}^{\mathcal{D}}(f, a) = \mathsf{app}^{\mathcal{D}}(f', a)$ for any $a \in \alpha^{\mathcal{D}}$. Moreover, the extensional equality of higher-order logic is—mutatis mutandis—exactly our $\approx_{\mathcal{D},(\alpha\to\beta)}$.
Now, the above extensionality requirement says that the data universe for $(\alpha \to \beta)$ can be viewed as a subset of $\{\ \mathsf{app}(\bullet_{(\alpha\to\beta)}, a) \mid a \in \alpha^{\mathcal{D}}\ \} \to \beta^{\mathcal{D}}$ or as a subset of $\alpha^{\mathcal{D}} \to \beta^{\mathcal{D}}$. Indeed, the total functions from α to β are isomorphic to these sets of functions.
Finally, the maximality requirement says that we need all functions from $\alpha^{\mathcal{D}} \to \beta^{\mathcal{D}}$ in the data universe for $(\alpha \to \beta)$, or at least those we can talk about.

Example 2.16 (Strange Labeled Transition Systems)

One thing we cannot model properly in our framework here are labeled transition systems, which require an additional layer on top for realizing μ-predicates, cf. e.g. Padawitz (2000).

Suppose we would try to model labeled transition systems with Boolean labels in the following fashion. Let $\mathsf{lts}, \mathsf{set} \in \mathbb{H}$ with $\mathsf{bool} < \mathsf{lts} \sim \mathsf{set}$ and $\mathsf{next}, \mathsf{in} \in \mathbb{D}$ with $\mathsf{next} : \mathsf{lts}, \mathsf{bool} \rightsquigarrow \mathsf{set}$ and $\mathsf{in} : \mathsf{lts}, \mathsf{set} \rightsquigarrow \mathsf{bool}$. Set $\mathbb{P} := \{\mathsf{next}(\bullet_{\mathsf{lts}}, b),\ \mathsf{in}(a, \bullet_{\mathsf{set}})\}$, where the former returns the set of all successor states labeled with b and the latter tests whether a is in the set. We get $\mathbb{E} = \{\mathsf{in}(a, \mathsf{next}(\bullet_{\mathsf{lts}}, b)),\ \mathsf{in}(a, \bullet_{\mathsf{set}})\}$.

The above definedness requirement says that $\mathsf{next}^{\mathcal{D}}$ must be total on $\mathsf{lts}^{\mathcal{D}} \times \mathsf{bool}^{\mathcal{D}}$ and $\mathsf{in}^{\mathcal{D}}$ must be total on $\mathsf{lts}^{\mathcal{D}} \times \mathsf{set}^{\mathcal{D}}$. The latter, however, is not appropriate because $\mathsf{in}^{\mathcal{D}}$ should be a predicate (i.e. a partial function with range $\{\mathsf{TRUE}\}$) and not a characteristic function (i.e. a total function with range $\{\mathsf{TRUE}, \mathsf{FALSE}\}$). Predicates and characteristic functions are interchangeable under the conjunction of following three assumptions.

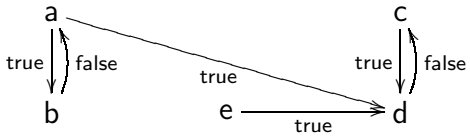
No μ-predicates: Predicates must not be considered as sets where only positive information is given and the intended meaning is the smallest consistent set.

Domain is a set: If the domain is a proper class, any characteristic function is a proper class while a predicate can be a set.

Domain already existing: As $\mathsf{lts} \sim \mathsf{set}$ we do not know what the mutual effect will be.

In the case of labeled transition systems, none of these assumptions is valid.

The condition (2) of Definition 2.5 says that $a \approx_{\mathcal{D},\mathsf{lts}} a'$ implies $\mathsf{next}^{\mathcal{D}}(a,b) \approx_{\mathcal{D},\mathsf{set}} \mathsf{next}^{\mathcal{D}}(a',b)$ for all $b \in \mathsf{bool}^{\mathcal{D}}$. It also says that $s \approx_{\mathcal{D},\mathsf{set}} s'$ implies that for any $a \in \mathsf{lts}^{\mathcal{D}}$ we have $\mathsf{in}^{\mathcal{D}}(a,s) = \mathsf{in}^{\mathcal{D}}(a',s')$. What it should say, however, is that $s \approx_{\mathcal{D},\mathsf{set}} s'$ implies that for any $a \in \mathsf{lts}^{\mathcal{D}}$ with $\mathsf{in}^{\mathcal{D}}(a,s)$ there is an $a' \in \mathsf{lts}^{\mathcal{D}}$ with $a \approx_{\mathsf{lts}} a'$ and $\mathsf{in}^{\mathcal{D}}(a',s')$. E.g., consider the following labeled transition system:



which should be specified via

$\mathsf{in}(\mathsf{b},\mathsf{next}(\mathsf{a},\mathsf{true}))$ $\quad$ $\mathsf{in}(\mathsf{d},\mathsf{next}(\mathsf{a},\mathsf{true}))$ $\quad$ $\mathsf{in}(\mathsf{d},\mathsf{next}(\mathsf{c},\mathsf{true}))$
$\mathsf{in}(\mathsf{a},\mathsf{next}(\mathsf{b},\mathsf{false}))$ $\quad$ $\mathsf{in}(\mathsf{d},\mathsf{next}(\mathsf{e},\mathsf{true}))$ $\quad$ $\mathsf{in}(\mathsf{c},\mathsf{next}(\mathsf{d},\mathsf{false}))$

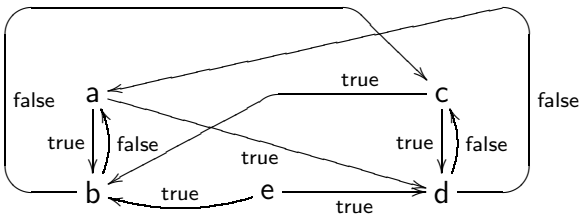
and render $\mathsf{a} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{c} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{e}$ and $\mathsf{b} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{d}$.

For our modeling here, the above specification would not be sufficient because 'in' would have to be total, and we would need something like:

$$\begin{aligned}
&\mathsf{in}(a,\mathsf{next}(\mathsf{a},b))=\mathsf{and}(\mathsf{or}(\mathsf{eq}(a,\mathsf{b}),\mathsf{eq}(a,\mathsf{d})),\mathsf{eq}(b,\mathsf{true}))\\
&\mathsf{in}(a,\mathsf{next}(\mathsf{b},b))=\mathsf{and}(\mathsf{eq}(a,\mathsf{a}),\mathsf{eq}(b,\mathsf{false}))\\
&\mathsf{in}(a,\mathsf{next}(\mathsf{c},b))=\mathsf{and}(\mathsf{eq}(a,\mathsf{d}),\mathsf{eq}(b,\mathsf{true}))\\
&\mathsf{in}(a,\mathsf{next}(\mathsf{d},b))=\mathsf{and}(\mathsf{eq}(a,\mathsf{c}),\mathsf{eq}(b,\mathsf{false}))\\
&\mathsf{in}(a,\mathsf{next}(\mathsf{e},b))=\mathsf{and}(\mathsf{eq}(a,\mathsf{d}),\mathsf{eq}(b,\mathsf{true}))
\end{aligned}$$

But then the maximum bisimulation is the identity because in case of $\mathsf{a} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{c}$, due to $\mathsf{in}(\mathsf{b},\mathsf{next}(\mathsf{c},\mathsf{true})) = \mathsf{false}$ there must be some $a \approx_{\mathcal{D},\mathsf{lts}} \mathsf{b}$ with $\mathsf{in}(a,\mathsf{next}(\mathsf{a},\mathsf{true})) = \mathsf{false}$, but the possible solutions $a = \mathsf{a}$, $a = \mathsf{c}$, and $a = \mathsf{e}$ are contradictory. Note that Definition 2.5 even requires $a = \mathsf{b}$ here instead of $a \approx_{\mathcal{D},\mathsf{lts}} \mathsf{b}$, because the step to a bisimular argument cannot be permitted for functions, but for predicates only; otherwise, besides other minor problems, the maximum bisimulation for $\mathbb{E}$ could be bigger than the maximum bisimulation for $\mathbb{P}$.

In order to get $\mathsf{a} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{c} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{e}$ and $\mathsf{b} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{d}$ with our modeling we would need



Note that in the approach of Roşu & Goguen (1998) even this would not suffice to get a bisimular to e, but to c only. This is because they do not have destructor patterns, but destructors only, and thus have to treat $\mathsf{in}(\bullet_{\mathsf{lts}}, s)$ as an additional pattern, resulting in $\mathsf{a} \not\approx_{\mathcal{D},\mathsf{lts}} \mathsf{e}$ due to $\mathsf{in}(\mathsf{a},\mathsf{next}(\mathsf{b},\mathsf{false})) = \mathsf{true}$ and $\mathsf{in}(\mathsf{e},\mathsf{next}(\mathsf{b},\mathsf{false})) = \mathsf{false}$. Regarding Requirement 2.10, however, our approach is not more useful than that of Roşu & Goguen (1998) in this silly case because from $\mathsf{a} \approx_{\mathcal{D},\mathsf{lts}} \mathsf{e}$ we get $\mathsf{a} = \mathsf{e}$ and then $\mathsf{true} = \mathsf{false}$. Thus, for consistency reasons, we will have to require that for all variables $x \notin \mathrm{ran}(\bullet)$ of a sort $h \in H$ that occur in a pattern p there also is a pattern $p\sigma$ where σ is a renaming with $\sigma(x) = \bullet_h$.

Speaking about consistency, it is important to note that there cannot be any consistent $\mathcal{D}$ at all that satisfies our three requirements from above, unless we restrict our specification language in non-adequate way: Consider $\mathsf{next}(\mathsf{r}, b) = \mathsf{Russell}$ and $\mathsf{in}(a, \mathsf{Russell}) = \mathsf{true} \longleftarrow \mathsf{in}(a, \mathsf{next}(a, \mathsf{true})) = \mathsf{false}$. This implies

$$\mathsf{in}(\mathsf{r}, \mathsf{next}(\mathsf{r}, \mathsf{true})) = \mathsf{true} \longleftarrow \mathsf{in}(\mathsf{r}, \mathsf{next}(\mathsf{r}, \mathsf{true})) = \mathsf{false}.$$

Since the destructor pattern for in requires totality of $\mathsf{in}^{\mathcal{D}}$, this leads to a contradiction. Thus, in this case, there would be no data universe that satisfies our definedness and maximality requirements, unless we excluded the above definition of r from the admissible ones, which renders r "undefinable".

Even when we, as we will do for the rest of this example, consider the reasonable specification with the predicate instead of the characteristic function, the existence of a data universe satisfying our three requirements is not at all clear:

The co algebraic view on labeled transition systems is the destructor

$$\mathsf{next} : \mathsf{lts} \to \mathsf{bool} \to \mathfrak{P}(\mathsf{lts})$$

and the proper class of labeled transition systems is the greatest fixpoint of the monotonic functor $F(X) = \mathsf{bool}^{\mathcal{D}} \to \mathfrak{P}(X)$ in the non-wellfounded set theory of Aczel (1988). We, however, have two problems with this fixpoint:
The first problem is that it is a proper class. This means we cannot work properly with it in set theory. E.g., every total function defined on it is a proper class, too, and thus any class of such functions is empty.
The second problem is that for new nullary function symbols say $\mathsf{a} : \mathsf{lts}$ and $\mathsf{all} : \mathsf{set}$ defined by $\mathsf{next}(\mathsf{a}, b) = \mathsf{all}$ and $\mathsf{in}(a, \mathsf{all})$ we have the problem that $\mathsf{a}^{\mathcal{D}}$ is not bisimular to any element of that fixpoint, simply because $\mathsf{all}^{\mathcal{D}}$ functions as a proper class and therefore cannot be an element of that fixpoint. This means that that fixpoint does not satisfy our above maximality requirement.
Thus, we need another fixpoint (1) in another set theory or (2) for another functor.

1. In order to be consistent, a set theory has to put some restrictions on set formation in order to avoid sets like the famous class named after Bertrand Russell, which is similar to the one above. The ingenious solution to this problem found by John von Neumann and others had been sufficient for half a century but then turned out to be not too well-suited for some tasks like ours here. While the non-wellfounded set theory of Aczel (1988) is simply an improvement of the standard one (i.e. it is just as consistent but has more sets), other set theories might deprive us of certain sets by restricting the axioms of comprehension, power-set, union, separation, subset, &c., but give us new sets that may be important for our work. The only results on new set theories I know are Forti &al. (1996) and others of the same authors who do not seem to have any interest in the practical usefulness of their theories or in explaining them to anybody interested in their practical application. It should be clear that we cannot settle these very sophisticated problems here.

2. The clearer solution is to choose a different functor. E.g., in this example, we could use the functor

   $$F(X) = \{\ f : \mathsf{bool}^{\mathcal{D}} \to \mathfrak{P}(X) \mid\ f \text{ is "definable" with the elements of } X\ \},$$

   which is finitary and monotonic and thus will have a least fixpoint at level ω, which is countable and therefore a set. While this is not the place to define "definable", the reader should also cf. the discussion on "Henkin" or "general" models in Example 2.12.

Our pragmatic solution to the problems with the establishment of hidden sorts is simply to assume that, for the destructor patterns and the admissible definitions we want to have, there is a partial algebra $\mathcal{D}$ satisfying our three requirements of definedness, extensionality, and maximality from above, and that there is a way to choose one of them as the intended one. In case that this choice should—contrary to our assumptions—turn out to be crucial for our notions of validity, then we have to add more requirements, and finally, when the field has become more common and better understood, we will have to solve the problem of whether and what data universes exist for given destructor patterns and given admissibility of definitions by some general means.

3 Fulfilledness and Rewriting

Definition 3.1 (Enrichment, Reduct)
Let Σ be a signature with $\mathbb{S}, \mathbb{K}, \mathbb{C}, \mathbb{D}, \mathbb{P}$ as sets of sorts, constants, constructors, destructors, patterns, resp..
Σ' is a *an enrichment* of Σ if Σ' is a signature whose sets of sorts, constants, constructors, destructors, patterns are a superclasses of the resp. sets of Σ and the arities of the common constants are identical in both signatures.
When Σ' is an enrichment of Σ and $\mathcal{B}$ is a Σ'-structure, then the Σ-*reduct* of $\mathcal{B}$ is the Σ-structure $\mathcal{A}$ given by $(\varsigma, s)^{\mathcal{A}} = (\varsigma, s)^{\mathcal{B}}$ for all $(\varsigma, s) \in \{\mathrm{GEN}, \mathrm{DAT}\} \times \mathbb{S}$ and $f^{\mathcal{A}} = f^{\mathcal{B}}$ for all $f \in \mathbb{K}$.
When $\mathcal{A}$ is a Σ-structure and Σ'' is the sub-signature of Σ that contains only the constants from $\mathbb{C}$ and $\mathbb{D}$, then the *data reduct of* $\mathcal{A}$ is the standard partial algebra $\mathcal{D}$ for Σ'' given by

$$s^{\mathcal{D}} = (\mathrm{DAT}, s)^{\mathcal{A}} \text{ for all } s \in \mathbb{S},$$
$$c^{\mathcal{D}} = c^{\mathcal{A}} \text{ for all } c \in \mathbb{C},$$

$d^{\mathcal{D}}$ is the minimal subset of $d^{\mathcal{A}}$ such that Requirement 2.4 is satisfied for all $d \in \mathbb{D}$.
Note that if such a minimal subset does not exist (because $d^{\mathcal{D}}$ has to have values outside $s^{\mathcal{D}}$), then the data reduct of $\mathcal{A}$ does not exist.

Note that the following definition is recursive on the sort of condition literals in the well-founded ordering $<$ introduced at the beginning of § 2.

Definition 3.2 (Fulfilledness)
Let Σ be a signature with $\mathbb{S}$, $\mathbb{V}$, $\mathbb{H}$, $\mathbb{K}$, $\mathbb{C}$, $\mathbb{E}$, as sets of sorts, visible sorts, hidden sorts, constant symbols, constructors, experiments, resp.. Let $\mathcal{D}$ be the data reduct of some Σ-algebra. Let X be a variable-system for $\mathbb{S}$, $\mathbb{K}$ with $\forall s \in \mathbb{S}.\ \mathrm{X}_{\mathrm{DAT},s} = \emptyset$. Let Σ' denote the signature that differs from Σ insofar as that the sets $\mathbb{K}$ and $\mathbb{C}$ of constants and constructors are extended to the sets $\mathbb{K}'$ and $\mathbb{C}'$ with a new nullary constant symbol $d : \rightarrow h$ for any hidden sort $h \in \mathbb{H}$ and any $d \in h^{\mathcal{D}}$. Note that the signature Σ' violates the rules of § 2 because it has constructors for hidden sorts. Let $\longrightarrow$ be a sort-invariant relation on $\mathcal{T}(\Sigma', \mathrm{X})$.
A list of condition literals over Σ', X is said to be *fulfilled w.r.t.* $\longrightarrow$ if each of its literals is.
A condition literal over Σ', X is said to be *fulfilled w.r.t.* $\longrightarrow$ if for all $s \in \mathbb{S}$ and $u, u' \in \mathcal{T}(\Sigma', \mathrm{X})_{\mathrm{GEN},s}$ if it has the form

Def u**:**

If $s \in \mathbb{V}$**:** There is a term t whose function symbols are constructors from $\mathbb{C}'$ and whose variables are of hidden sort, and a substitution $\sigma : \mathcal{V}(t) \rightarrow \mathcal{T}(\Sigma', \mathrm{X})$ such that $u \xrightarrow{*} t\sigma$ and $\mathrm{Def}(x\sigma)$ is fulfilled w.r.t. $\longrightarrow$ for each $x \in \mathcal{V}(t)$.

If $s \in \mathbb{H}$**:** For any $v \in \mathbb{V}$, any experiment $\left(e \longleftarrow L_0, \ldots, L_{m-1} \right) \in \mathbb{E}^v_s$ over Σ, V where w_j, w'_j are the terms of L_j, and any $\sigma : \mathcal{V}(e) \rightarrow \mathcal{T}(\Sigma', \mathrm{X})$ with $\sigma(\bullet_s) = u$ and $\forall x \in \mathcal{V}(e) \backslash \{\bullet_s\}.\ \sigma(x) \in \mathcal{GT}(\Sigma')_{\mathrm{DAT}}$, there either is some $i \prec m$ such that
$\left(\mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{i-1}, \mathrm{Def}\, w'_{i-1}, L_{i-1}, \mathrm{Def}\, w_i, \mathrm{Def}\, w'_i, \overline{L_i} \right)\sigma$
is fulfilled w.r.t. $\longrightarrow$ or otherwise
$\left(\mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1}, \mathrm{Def}\, e \right)\sigma$
is fulfilled w.r.t. $\longrightarrow$.

$u{=}u'$**:**

If $s \in \mathbb{V}$**:** There is a term t whose function symbols are constructors from $\mathbb{C}'$ and whose variables are of hidden sort, and two substitutions $\sigma, \sigma' : \mathcal{V}(t) \to \mathcal{T}(\Sigma', \mathrm{X})$ such that $u \xrightarrow{*} t\sigma$, $u' \xrightarrow{*} t\sigma'$, and $x\sigma{=}x\sigma'$ is fulfilled w.r.t. $\longrightarrow$ for each $x \in \mathcal{V}(t)$.

If $s \in \mathbb{H}$**:** For any $v \in \mathbb{V}$, any experiment $\left(\; e \longleftarrow L_0, \ldots, L_{m-1} \; \right) \in \mathbb{E}^v_s$ over Σ, V where w_j, w'_j are the terms of L_j, and any $\sigma, \sigma' : \mathcal{V}(e) \to \mathcal{T}(\Sigma', \mathrm{X})$ with $\sigma(\bullet_s) = u$, $\sigma'(\bullet_s) = u'$, and $\forall x \in \mathcal{V}(e) \backslash \{\bullet_s\}.\ \sigma(x) = \sigma'(x) \in \mathcal{GT}(\Sigma')_{\mathrm{DAT}}$, there either are some $i, i' \prec m$ such that
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{i-1}, \mathrm{Def}\, w'_{i-1}, L_{i-1}, \mathrm{Def}\, w_i, \mathrm{Def}\, w'_i, \overline{L_i} \; \right)\sigma$,
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{i'-1}, \mathrm{Def}\, w'_{i'-1}, L_{i'-1}, \mathrm{Def}\, w_{i'}, \mathrm{Def}\, w'_{i'}, \overline{L_{i'}} \; \right)\sigma'$
is fulfilled w.r.t. $\longrightarrow$ or otherwise
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1} \; \right)\sigma$,
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1} \; \right)\sigma'$, $e\sigma{=}e\sigma'$
is fulfilled w.r.t. $\longrightarrow$.

$u{\neq}u'$**:**

If $s \in \mathbb{V}$**:** There are terms t, t' whose function symbols are constructors from $\mathbb{C}'$ and whose variables are of hidden sort, and two substitutions $\sigma : \mathcal{V}(t) \to \mathcal{T}(\Sigma', \mathrm{X})$, $\sigma' : \mathcal{V}(t') \to \mathcal{T}(\Sigma', \mathrm{X})$, such that $u \xrightarrow{*} t\sigma$, $u' \xrightarrow{*} t'\sigma'$, and either t and t' are clashing or else t and t' are equal and there is some $x \in \mathcal{V}_{\mathrm{GEN},h}(t)$ such that $h \in \mathbb{H}$ and $x\sigma{\neq}x\sigma'$ is fulfilled w.r.t. $\longrightarrow$.

If $s \in \mathbb{H}$**:** For some $v \in \mathbb{V}$, some experiment $\left(\; e \longleftarrow L_0, \ldots, L_{m-1} \; \right) \in \mathbb{E}^v_s$ over Σ, V where w_j, w'_j are the terms of L_j, and some $\sigma, \sigma' : \mathcal{V}(e) \to \mathcal{T}(\Sigma', \mathrm{X})$ with $\sigma(\bullet_s) = u$, $\sigma'(\bullet_s) = u'$, and $\forall x \in \mathcal{V}(e) \backslash \{\bullet_s\}.\ \sigma(x) = \sigma'(x) \in \mathcal{GT}(\Sigma')_{\mathrm{DAT}}$, there either is some $i \prec m$ such that
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{i-1}, \mathrm{Def}\, w'_{i-1}, L_{i-1}, \mathrm{Def}\, w_i, \mathrm{Def}\, w'_i, \overline{L_i} \; \right)\sigma$,
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1} \; \right)\sigma'$
or
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1} \; \right)\sigma$,
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{i-1}, \mathrm{Def}\, w'_{i-1}, L_{i-1}, \mathrm{Def}\, w_i, \mathrm{Def}\, w'_i, \overline{L_i} \; \right)\sigma'$
is fulfilled w.r.t. $\longrightarrow$ or otherwise
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1} \; \right)\sigma$,
$\left(\; \mathrm{Def}\, w_0, \mathrm{Def}\, w'_0, L_0, \ldots, \mathrm{Def}\, w_{m-1}, \mathrm{Def}\, w'_{m-1}, L_{m-1} \; \right)\sigma'$, $e\sigma{\neq}e\sigma'$
is fulfilled w.r.t. $\longrightarrow$.

4 Basic Notions for Σ-algebras

Note that the following definition differs from the standard one.

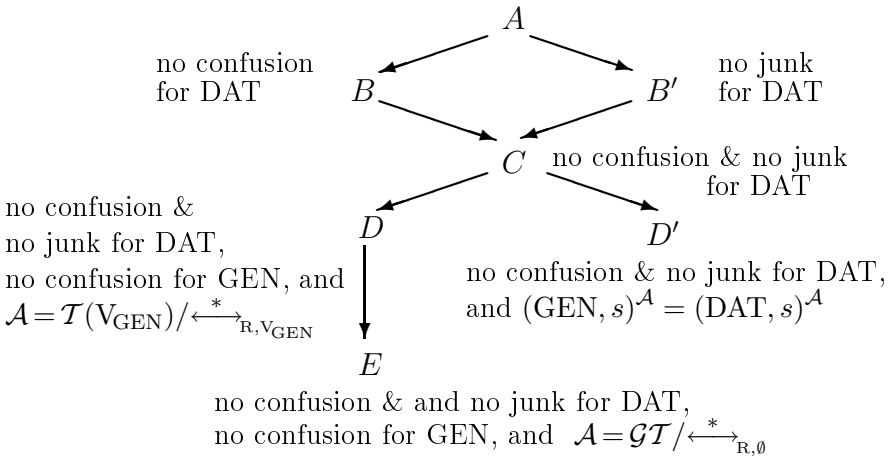
Definition 4.1 (Σ-Homomorphism)
Let Σ be a signature, with $\mathbb{S}$ and $\mathbb{K}$ as sets of sorts and constants, resp..
A Σ-*homomorphism from* $\mathcal{A}$ *to* $\mathcal{B}$ is a triple written $h::\mathcal{A}\to\mathcal{B}$ of
two Σ-structures $\mathcal{A}$ and $\mathcal{B}$ *whose data reducts are equal (!!!)* and
an $\mathbb{S}$-sorted family $h = (h_s)_{s\in\mathbb{S}}$ of functions $h_s : (\mathrm{GEN}, s)^{\mathcal{A}} \to (\mathrm{GEN}, s)^{\mathcal{B}}$
that is compatible with Σ in the following sense:
For $f\in\mathbb{K}$ with $f : s_0, \ldots, s_{n-1} \rightsquigarrow s_n$ and for $a_0 \in (\mathrm{GEN}, s_0)^{\mathcal{A}}$, $\ldots$, $a_{n-1} \in (\mathrm{GEN}, s_{n-1})^{\mathcal{A}}$
we have $h_{s_n}(f^{\mathcal{A}}(a_0, \ldots, a_{n-1})) = f^{\mathcal{B}}(h_{s_0}(a_0), \ldots, h_{s_{n-1}}(a_{n-1}))$, and
for all $s \in \mathbb{S}$ and $d \in (\mathrm{DAT}, s)^{\mathcal{A}}$ we have $h_s(d) = d$.

Definition 4.2 (Initial, Free)
Let X be a variable-system for $\mathbb{S}$ and $\mathbb{K}$ of the signature Σ.
Let $\mathcal{A}$ be a Σ-structure and K a class of Σ-structures.
$\mathcal{A}$ is *initial in* K if $\mathcal{A}$ is in K and, for each $\mathcal{B}$ in K, there is a unique Σ-homomorphism $h::\mathcal{A}\to\mathcal{B}$.
$\mathcal{A}$ is *free in* K *over* X if there is some $\iota : \mathrm{X} \to \mathcal{A}$ such that $\mathcal{A}$ is free in K over X w.r.t. ι.
$\mathcal{A}$ is *free in* K *over* X *w.r.t.* ι if $\mathcal{A}$ is in K and $\mathcal{A}$ is free for K over X w.r.t. ι.
$\mathcal{A}$ is *free for* K *over* X *w.r.t.* ι if for each $\mathcal{B}$ in K and $\tau : \mathrm{X} \to \mathcal{B}$ there is a unique Σ-homomorphism $h::\mathcal{A}\to\mathcal{B}$ with $\tau_{\varsigma,s} = \iota_{\varsigma,s} \circ h_s$ for each $(\varsigma, s) \in \{\mathrm{GEN}, \mathrm{DAT}\}\times\mathbb{S}$.

5 Four Notions of Validity

Please! Never again write a paper with seven notions of validity!

— Deepak Kapur, 1996



In Wirth & Gramlich (1994b) and still in Wirth (1997), we had seven notions of (inductive) validity. After application and consideration for years, we would now say that one or two (type C and maybe type D) are really useful, two more are important because they are still common (type E, D'), and the remaining three (type A, B, and B') are only interesting for the history of inductive validity and will not be treated in this paper, although they were once used by other authors as in Kounalis & Rusinowitch (1990) and Bouhoula &al. (1992). The names of the types were chosen such that, roughly speaking, if T precedes T' in the alphabet, then type-T validity of a formula implies type-T' validity of it.

Specifications should express only what is important for the specifier.
A proper semantics for such partial specifications must be based on a class of different models instead of a single one.
A free or initial model can serve for a minimal implementation but is not adequate for defining the semantics of partial specifications.

— Robert Bookhade, 1999

Definition 5.1 (Specification, Validity)
Let Σ be a signature with $\mathbb{S}$ and $\mathbb{K}$ as sets of sorts and constants, resp.. Let $\mathcal{D}$ be the data reduct of some Σ-structure. Let R be a set of formulas over Σ. We will call $(\Sigma,\mathcal{D},R)$ a *specification*. Let $\mathcal{A}$ be a Σ-structure such that R is valid in $\mathcal{A}$.
Now, $\mathcal{A}$ is a *model of* $(\Sigma,\mathcal{D},R)$ *of type*

- C if the data reduct of $\mathcal{A}$ is $\mathcal{D}$.
- D if for some variable-system X for $\mathbb{S}$, $\mathbb{K}$ with $\forall s\in\mathbb{S}.\ \mathrm{X}_{\mathrm{DAT},s}=\emptyset$, $\mathcal{A}$ is free in the class of models of $(\Sigma,\mathcal{D},R)$ of type C over X.
- E if $\mathcal{A}$ is initial in the class of models of $(\Sigma,\mathcal{D},R)$ of type C.
- D' if $\mathcal{A}$ is a model of $(\Sigma,\mathcal{D},R)$ of type C, and $(\mathrm{DAT},s)^{\mathcal{A}}=(\mathrm{GEN},s)^{\mathcal{A}}$ for each $s\in\mathbb{S}$; i.e. the general universes coincide with the data universes.

Finally, for T being any of the above types, a formula is *type-T valid w.r.t.* $(\Sigma,\mathcal{D},R)$ if it is valid in all models of $(\Sigma,\mathcal{D},R)$ of type T.

Corollary 5.2 *If a formula is type-C valid w.r.t.* $(\Sigma, \mathcal{D}, R)$*, then it is also type-D, type-E, and type-D′ valid w.r.t.* $(\Sigma, \mathcal{D}, R)$*.*

Definition 5.3 (Extension)
$(\Sigma', \mathcal{D}', R')$ is an *extension* of of the specification $(\Sigma, \mathcal{D}, R)$ if $(\Sigma', \mathcal{D}', R')$ is a specification such that Σ' is a an enrichment of Σ, $s^{\mathcal{D}'} = s^{\mathcal{D}}$ for all $s \in \mathbb{S}$, $c^{\mathcal{D}'} = c^{\mathcal{D}}$ for all $c \in \mathbb{C}$, and $d^{\mathcal{D}'} = d^{\mathcal{D}}$ for all $d \in \mathbb{D}$, where $\mathbb{S}$, $\mathbb{C}$, $\mathbb{D}$ are the sets of sorts, constructors, destructors of Σ, resp., and $R \subseteq R'$.
Such an extension is called *type-T consistent* if the Σ-reduct of any model of $(\Sigma', \mathcal{D}', R')$ of type-T is a model of $(\Sigma, \mathcal{D}, R)$ of type-T.

Note that consistent extensions (where the reducts of new models must be old ones) are somehow the converse of the well-known *conservative extensions*, where old models must be extensible to new models.

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